

# Jaringan dan Infrastruktur Sistem Cerdas (JSC)

## Pertemuan 9 : Praktik Pengolahan Data

Alauddin Maulana Hirzan

Fakultas Teknologi Informasi dan Komunikasi  
Universitas Semarang

# Outline

Jaringan dan  
Infrastruktur  
Sistem  
Cerdas  
(JSC)

Alauddin  
Maulana  
Hirzan

Konsep Data  
Mentah

Teknik  
Pengolahan  
Data

Penyimpanan  
Data

Lastly

- 1 Konsep Data Mentah
- 2 Teknik Pengolahan Data
- 3 Penyimpanan Data
- 4 Lastly

# Sumber Data

Data mentah (*raw data*) adalah data yang diperoleh langsung dari sumber tanpa melalui proses pengolahan. Dalam konteks sistem cerdas dan jaringan, sumber utama meliputi:

- **Sensor IoT :**
  - Sensor menghasilkan data kontinu (time-series)
    - Suhu (temperature)
    - Kelembaban (humidity)
    - Tekanan (pressure)
  - Karakteristik:
    - Real-time
    - Rentan noise
    - Sampling periodik

- Network Logs
  - Log jaringan mencatat aktivitas sistem:
    - Traffic data (packet size, latency)
    - Access logs
    - Error logs
  - Karakteristik:
    - Volume besar
    - Tidak selalu terstruktur
    - Mengandung anomali

# Permasalahan Umum

Jaringan dan  
Infrastruktur  
Sistem  
Cerdas  
(JSC)

Alauddin  
Maulana  
Hirzan

Konsep Data  
Mentah

Teknik  
Pengolahan  
Data

Penyimpanan  
Data

Lastly

## 1 Noise (Gangguan Sinyal)

- Noise adalah fluktuasi acak yang tidak merepresentasikan kondisi sebenarnya.
- Contoh: Sensor suhu membaca  $25^{\circ}\text{C}$  → tiba-tiba  $80^{\circ}\text{C}$  → kembali  $26^{\circ}\text{C}$

## 2 Outlier

- Nilai ekstrem yang jauh dari distribusi normal.
- Contoh: Data suhu normal:  $24\text{--}28^{\circ}\text{C}$ , Outlier:  $100^{\circ}\text{C}$

## 3 Data Spike

- Lonjakan tiba-tiba dalam waktu singkat.
- Contoh: Traffic jaringan melonjak drastis dalam 1 detik

# Contoh

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Infrastruktur  
Sistem  
Cerdas  
(JSC)

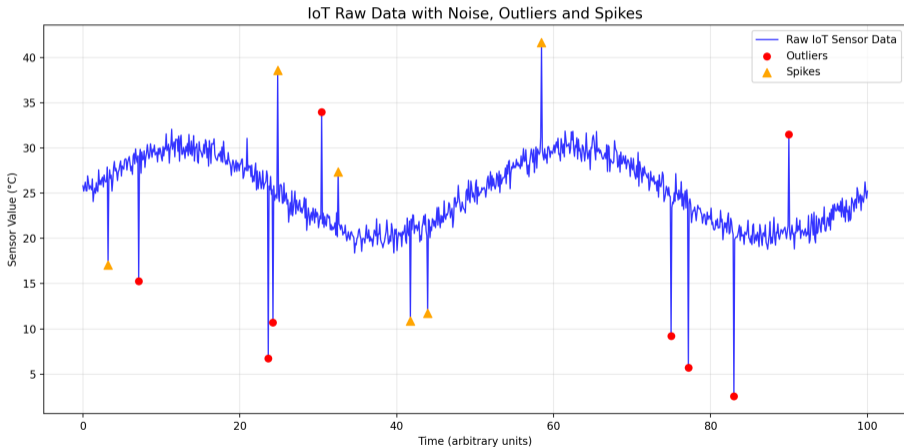
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Konsep Data  
Mentah

Teknik  
Pengolahan  
Data

Penyimpanan  
Data

Lastly



# Teknik Pengolahan Data

Jaringan dan  
Infrastruktur  
Sistem  
Cerdas  
(JSC)

Alauddin  
Maulana  
Hirzan

Konsep Data  
Mentah

Teknik  
Pengolahan  
Data

Penyimpanan  
Data

Lastly

## Generate Random Data - Bagian 1

```
import numpy as np
import matplotlib.pyplot as plt

# Generate synthetic IoT sensor data (e.g. temperature over time)
np.random.seed(42)
time = np.linspace(0, 100, 1000) # 1000 data points

# Base signal: normal trend + daily-ish variation
base = 25 + 5 * np.sin(2 * np.pi * time / 50)

# Add Gaussian noise
noise = np.random.normal(0, 0.8, len(time))
```

# Teknik Pengolahan Data

Jaringan dan  
Infrastruktur  
Sistem  
Cerdas  
(JSC)

Alauddin  
Maulana  
Hirzan

Konsep Data  
Mentah

Teknik  
Pengolahan  
Data

Penyimpanan  
Data

Lastly

## Generate Random Data - Bagian 2

```
# Add random outliers (rare large deviations)
outliers = np.random.normal(0, 0.3, len(time))
outlier_idx = np.random.choice(len(time), 8, replace=False)
outliers[outlier_idx] += np.random.choice([-15, 12, -18, 14], 8)

# Add spikes (short sudden bursts)
spikes = np.zeros(len(time))
spike_idx = np.random.choice(len(time), 6, replace=False)
spikes[spike_idx] = np.random.choice([8, -10, 12, -9], 6)
```

# Teknik Pengolahan Data

Jaringan dan  
Infrastruktur  
Sistem  
Cerdas  
(JSC)

Alauddin  
Maulana  
Hirzan

Konsep Data  
Mentah

Teknik  
Pengolahan  
Data

Penyimpanan  
Data

Lastly

## Generate Random Data - Bagian 3

```
# Final raw IoT data
y = base + noise + outliers + spikes
X = np.linspace(0, 100, 1000).reshape(-1, 1)

print(X[:10])
print(y[:10])
```

# Ilustrasi

Jaringan dan  
Infrastruktur  
Sistem  
Cerdas  
(JSC)

Alauddin  
Maulana  
Hirzan

Konsep Data  
Mentah

Teknik  
Pengolahan  
Data

Penyimpanan  
Data

Lastly

```
[4]: import numpy as np
import matplotlib.pyplot as plt

# Generate synthetic IoT sensor data (e.g. temperature over time)
np.random.seed(42)
time = np.linspace(0, 100, 1000) # 1000 data points

# Base signal: normal trend + daily-ish variation
base = 25 + 5 * np.sin(2 * np.pi * time / 50)

# Add Gaussian noise
noise = np.random.normal(0, 0.8, len(time))
# Add random outliers (rare large deviations)
outliers = np.random.normal(0, 0.3, len(time))
outlier_idx = np.random.choice(len(time), 8, replace=False)
outliers[outlier_idx] += np.random.choice([-15, 12, -18, 14], 8)

# Add spikes (short sudden bursts)
spikes = np.zeros(len(time))
spike_idx = np.random.choice(len(time), 6, replace=False)
spikes[spike_idx] = np.random.choice([8, -10, 12, -9], 6)

# Final raw IoT data
y = base + noise + outliers + spikes
X = np.linspace(0, 100, 1000).reshape(-1, 1)

print(X[:10])
print(y[:10])

[[0.         ]
 [0.1001001 ]
 [0.2002002 ]
 [0.3003003 ]
 [0.4004004 ]
 [0.5005005 ]
 [0.6006006 ]
 [0.7007007 ]
 [0.8008008 ]
 [0.9009009 ]]
[25.81717795 25.22067175 25.66181617 26.21298232 25.27361715 25.2450025
 26.90893854 26.24419387 25.4415955 25.83832183]
```

# Teknik Filtering

## Moving Average Filtering

```
import pandas as pd

def moving_average(y, window_size=15):
    return pd.Series(y).rolling(window=window_size,
                                center=True,
                                min_periods=1).mean().values

window_size = 15
y_filtered = moving_average(y, window_size)
```

# Teknik Filtering

## Menampilkan Gambar 1

```
plt.plot(X.flatten(), y, 'b-',  
         linewidth=1.0, alpha=0.6,  
         label='Raw IoT Data (with noise, spikes & outliers)')  
plt.plot(X.flatten(), y_filtered, 'r-',  
         linewidth=2.0,  
         label=f'Moving Average Filter (window={window_size})')  
  
plt.scatter(X[spike_idx].flatten(), y[spike_idx],  
            color='orange', s=70, marker='^',  
            zorder=5, label='Spikes')
```

# Teknik Filtering

## Menampilkan Gambar 2

```
plt.scatter(X[outlier_idx].flatten(), y[outlier_idx],  
            color='red', s=50, zorder=5, label='Outliers')  
  
plt.title('IoT Raw Data vs Moving Average Filtered Data',  
         fontsize=14)  
plt.xlabel('Time (X)')  
plt.ylabel('Sensor Value (°C)')  
plt.grid(True, alpha=0.3)  
plt.legend()  
plt.tight_layout()  
plt.show()
```

# Ilustrasi

Jaringan dan  
Infrastruktur  
Sistem  
Cerdas  
(JSC)

Alauddin  
Maulana  
Hirzan

Konsep Data  
Mentah

Teknik  
Pengolahan  
Data

Penyimpanan  
Data

Lastly

```
[6]: import pandas as pd

def moving_average(y, window_size=15):
    return pd.Series(y).rolling(window=window_size, center=True, min_periods=1).mean().values

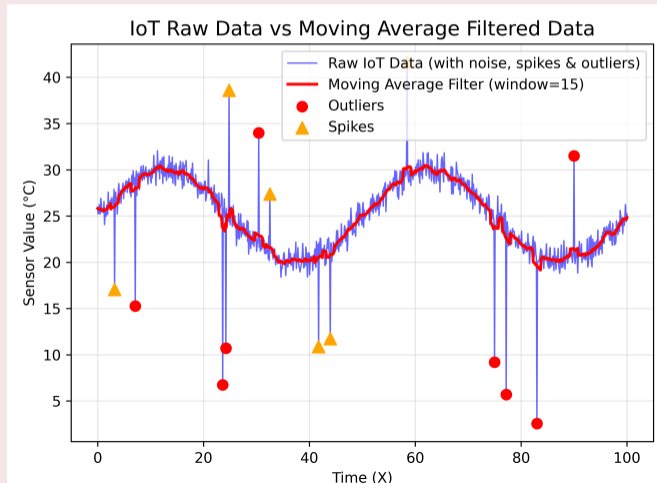
window_size = 15
y_filtered = moving_average(y, window_size)

[14]: plt.plot(X.flatten(), y, "b-", linewidth=1.0, alpha=0.6, label='Raw IoT Data (with noise, spikes & outliers)')
plt.plot(X.flatten(), y_filtered, 'r-', linewidth=2.0, label=f'Moving Average Filter (window={window_size})')

# Highlight anomalies
plt.scatter(X[outlier_idx].flatten(), y[outlier_idx],
            color='red', s=50, zorder=5, label='Outliers')
plt.scatter(X[spike_idx].flatten(), y[spike_idx],
            color='orange', s=70, marker='^', zorder=5, label='Spikes')

plt.title('IoT Raw Data vs Moving Average Filtered Data', fontsize=14)
plt.xlabel('Time (X)')
plt.ylabel('Sensor Value (°C)')
plt.grid(True, alpha=0.3)
plt.legend()
plt.tight_layout()
plt.savefig("moving-average.png", dpi=600)
```

## Moving Average



# Teknik Filtering

## Low Pass Filtering

```
from scipy import signal

def low_pass_filter(y, cutoff_freq=0.05, fs=1.0, order=4):
    nyquist = fs / 2
    normal_cutoff = cutoff_freq / nyquist
    b, a = signal.butter(order, normal_cutoff, btype='low',
                        analog=False)
    y_filtered = signal.filtfilt(b, a, y) # Zero-phase filtering
    return y_filtered

# Apply Low-Pass Filter
y_filtered = low_pass_filter(y, cutoff_freq=0.08, fs=1.0, order=5)
```

# Teknik Filtering

## Menampilkan Gambar 1

```
plt.plot(X.flatten(), y, 'b-',  
         linewidth=1.0, alpha=0.6,  
         label='Raw IoT Data (with noise, spikes & outliers)')  
plt.plot(X.flatten(), y_filtered, 'r-',  
         linewidth=2.0,  
         label=f'Low Pass Filter (window={window_size})')  
  
plt.scatter(X[spike_idx].flatten(), y[spike_idx],  
            color='orange', s=70, marker='^',  
            zorder=5, label='Spikes')
```

# Teknik Filtering

## Menampilkan Gambar 2

```
plt.scatter(X[outlier_idx].flatten(), y[outlier_idx],  
            color='red', s=50, zorder=5, label='Outliers')  
  
plt.title('IoT Raw Data vs Low Pass Filtered Data',  
          fontsize=14)  
plt.xlabel('Time (X)')  
plt.ylabel('Sensor Value (°C)')  
plt.grid(True, alpha=0.3)  
plt.legend()  
plt.tight_layout()  
plt.show()
```

# Ilustrasi

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Infrastruktur  
Sistem  
Cerdas  
(JSC)

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Maulana  
Hirzan

Konsep Data  
Mentah

Teknik  
Pengolahan  
Data

Penyimpanan  
Data

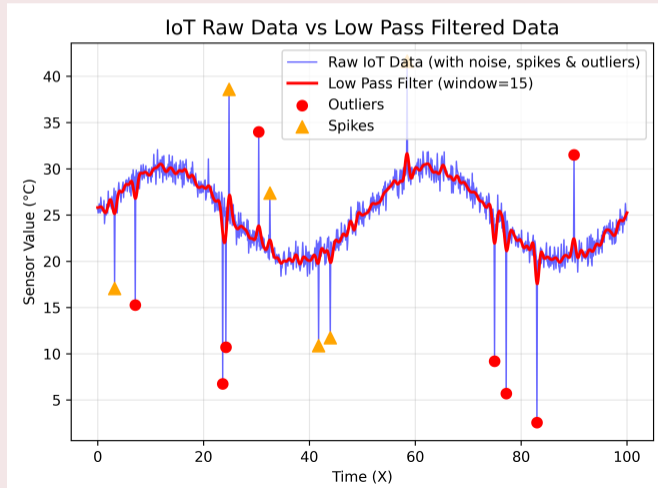
Lastly

```
[16]: from scipy import signal

def low_pass_filter(y, cutoff_freq=0.05, fs=1.0, order=4):
    nyquist = fs / 2
    normal_cutoff = cutoff_freq / nyquist
    b, a = signal.butter(order, normal_cutoff, btype='low', analog=False)
    y_filtered = signal.filtfilt(b, a, y) # Zero-phase filtering
    return y_filtered

# Apply Low-Pass Filter
y_filtered = low_pass_filter(y, cutoff_freq=0.08, fs=1.0, order=5)
```

## Low Pass



# Teknik Filtering

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Infrastruktur  
Sistem  
Cerdas  
(JSC)

Alauddin  
Maulana  
Hirzan

Konsep Data  
Mentah

Teknik  
Pengolahan  
Data

Penyimpanan  
Data

Lastly

## Median Filtering

```
from scipy import ndimage

def median_filter(y, window_size=15):
    return ndimage.median_filter(y, size=window_size)

# Apply Median Filter
window_size = 15
y_filtered = median_filter(y, window_size)
```

# Teknik Filtering

## Menampilkan Gambar 1

```
plt.plot(X.flatten(), y, 'b-',  
         linewidth=1.0, alpha=0.6,  
         label='Raw IoT Data (with noise, spikes & outliers)')  
plt.plot(X.flatten(), y_filtered, 'r-',  
         linewidth=2.0,  
         label=f'Median Filter (window={window_size})')  
  
plt.scatter(X[spike_idx].flatten(), y[spike_idx],  
            color='orange', s=70, marker='^',  
            zorder=5, label='Spikes')
```

# Teknik Filtering

## Menampilkan Gambar 2

```
plt.scatter(X[outlier_idx].flatten(), y[outlier_idx],  
            color='red', s=50, zorder=5, label='Outliers')  
  
plt.title('IoT Raw Data vs Median Filtered Data',  
          fontsize=14)  
plt.xlabel('Time (X)')  
plt.ylabel('Sensor Value (°C)')  
plt.grid(True, alpha=0.3)  
plt.legend()  
plt.tight_layout()  
plt.show()
```

# Ilustrasi

Jaringan dan  
Infrastruktur  
Sistem  
Cerdas  
(JSC)

Alauddin  
Maulana  
Hirzan

Konsep Data  
Mentah

Teknik  
Pengolahan  
Data

Penyimpanan  
Data

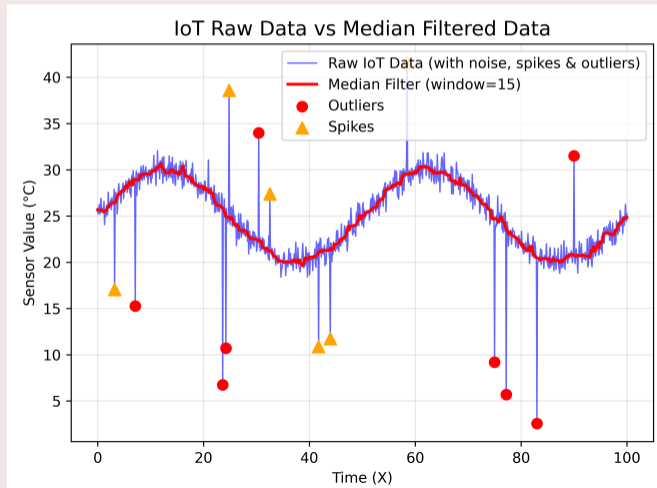
Lastly

```
[21]: from scipy import ndimage

def median_filter(y, window_size=15):
    return ndimage.median_filter(y, size=window_size)

# Apply Median Filter
window_size = 15
y_filtered = median_filter(y, window_size)
```

## Median



## Mengapa Data Perlu Disimpan

Penyimpanan data merupakan komponen penting dalam sistem cerdas, khususnya pada IoT dan jaringan.

- 1 Analisis Historis**
  - Data yang tersimpan memungkinkan analisis pola masa lalu (time-series analysis)
- 2 Training Model**
  - Machine learning membutuhkan data historis sebagai dataset
- 3 Monitoring**
  - Data real-time dan historis

# Jenis Penyimpanan

## 1 Penyimpanan Lokal

- File CSV
- File JSON

## 2 Database

- SQL (Relation Database)
  - Data terstruktur (tabel)
  - Mendukung query kompleks (JOIN, aggregation)
- NoSQL Database
  - Tidak berbasis tabel
  - Format dokumen (JSON-like)
  - Fleksibel untuk data IoT

## 3 Cloud Storage

- Firebase
- AWS IoT

# Terima Kasih